

# Pointer-based Data Structures (1/5)

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# Course Info: Pointer-based Data Structures

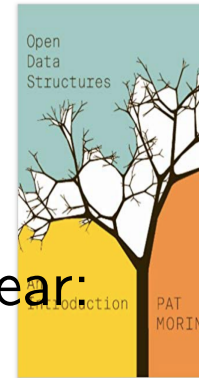
## Schedule:

- Lec. 1: Intro, BSTs review, Scapegoat trees.
- Lec. 2: Splay trees, dynamic optimality.
- Lec. 3: Link-cut trees.
- Lec. 4 & Lec. 5: Dynamization of static pointer-based DSs.  
Persistence for dynamic pointer-based DSs.

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Some books:

- R. Cormen, C. Leiserson, R. Rivest, C. Stein "Introduction to Algorithms, 3rd Edition" (The MIT Press) 2009.
- Pat Morin "Open Data structures" <https://opendatastructures.org>



Conferences where most work on data structures appear:

- Foundations of Computer Science (FOCS),
- Symposium On Discrete Algorithms (SODA),
- International Colloquium on Automata, Languages and Programming (ICALP),
- European Symposium on Algorithms (ESA),
- International Symposium on Algorithms and Computation (ISAAC),
- Symposium on Theoretical Aspects of Computer Science (STACS),
- Scandinavian Symposium and Workshops on Algorithm Theory (SWAT),
- Algorithms and Data Structures Symposium (WADS)

# Dynamic Sets

	BST	RB-tree	Scapegoat tree	Splay tree
SEARCH( $S, k$ )	$O(h)$	$O(\log n)$	$O(\log n)$	$O(\log n)$
MINIMUM( $S$ )	$O(h)$	$O(\log n)$	$O(\log n)$	$O(\log n)$
MAXIMUM( $S$ )	$O(h)$	$O(\log n)$	$O(\log n)$	$O(\log n)$
SUCCESSOR( $S, x$ )	$O(h)$	$O(\log n)$	$O(\log n)$	$O(\log n)$
PREDECESSOR( $S, x$ )	$O(h)$	$O(\log n)$	$O(\log n)$	$O(\log n)$
INSERT( $S, x$ )	$O(h)$	$O(\log n)$	$O(\log n)$	$O(\log n)$
DELETE( $S, x$ )	$O(h)$	$O(\log n)$	$O(\log n)$	$O(\log n)$

Lec. 1 & 2

— worst-case time

— amortized worst-case time

# Exercises

- (An alternative in-order walk in BST) Prove that the following procedure in a BST of size  $n$  can be carried out in  $\Theta(n)$  time: Find the minimum element in the tree, write it down, then  $n - 1$  times find the successor of the last element written and write the result down.
- How do we Join two BSTs? ( $\text{Join}(T_1, x, T_2)$  takes two BSTs, such that all the keys of  $T_1$  are at most  $x$ , and all the keys of  $T_2$  are greater than  $x$ , and returns a BST whose keys are union of the sets of keys of  $T_1$  and  $T_2$ ).
- How do we Join Red-Black Trees efficiently? (here both initial and final tree must be red-black)
- How do we Join Scapegoat trees efficiently?
- (\*) Describe a Rebuild procedure (used in Scapegoat trees) that takes  $o(n)$  space in addition to the space taken by the tree itself.

# Reading on BSTs, RB trees, Scapegoat trees

- BSTs and Red-Black trees:
  - R. Cormen, C. Leiserson, R. Rivest, C. Stein "Introduction to Algorithms, 3rd Ed." (The MIT Press) 2009 + Russian translation
  - original1: R. Bayer and E. M. McCreight. Organization and maintenance of large ordered indexes. Acta Informatica, 1(3):173–189, 1972.
  - original2: Leo J. Guibas and Robert Sedgwick. A dichromatic framework for balanced trees. In Proc. 19th Annual Symposium on Foundations of Computer Science, pages 8–21, 1978.
- Scapegoat trees:
  - Pat Morin "Open Data Structures"
  - Jeff Erikson's lecture notes:  
<http://jeffe.cs.illinois.edu/teaching/datastructures/notes/02-scapegoat-splay.pdf>
  - original1: Arne Andersson. General balanced trees. J. Algorithms 30:1–28, 1999.
  - original2: I. Galperin and R. Rivest. Scapegoat trees. Proc. 4th Annu. ACM-SIAM Sympos. Discrete Algorithms, 165–174, 1993.