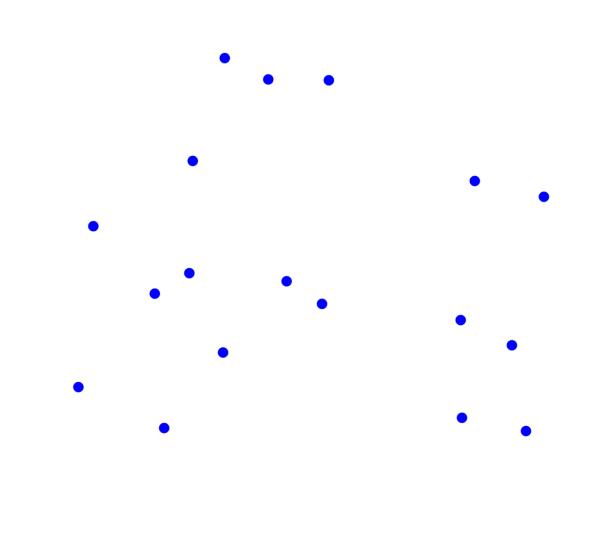
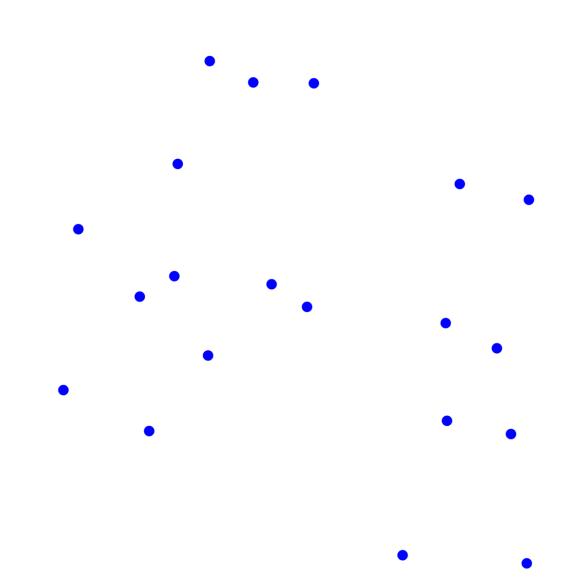
Similarity Search

Largely based on a paper joint with Alexandr Andoni (Columbia), Piotr Indyk (MIT), Thijs Laarhoven (TU Eindhoven) and Ludwig Schmidt (MIT)

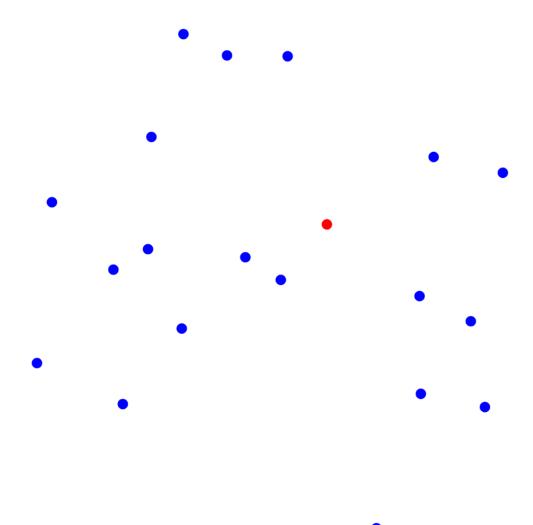
- Near Neighbor Search
- Dataset: n points in R^d, r > 0



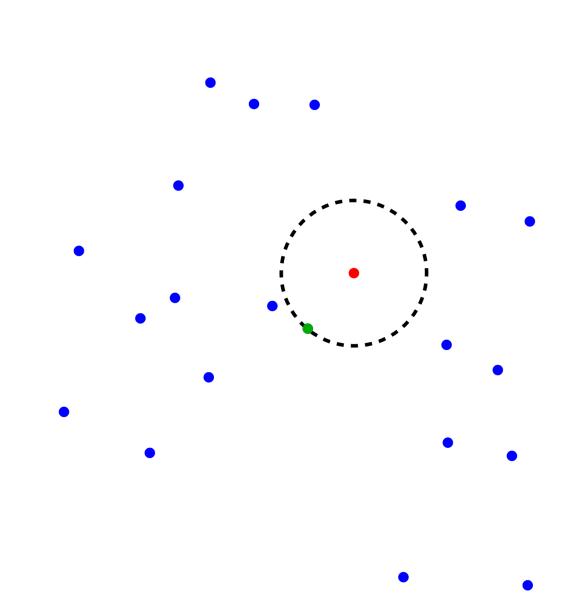
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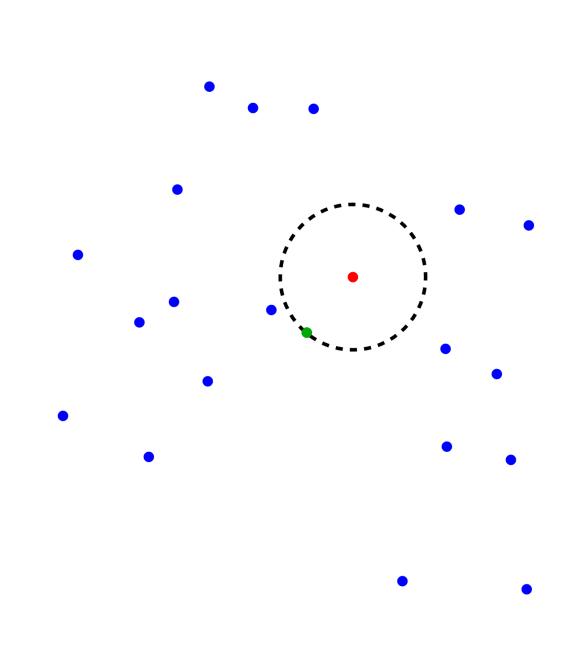
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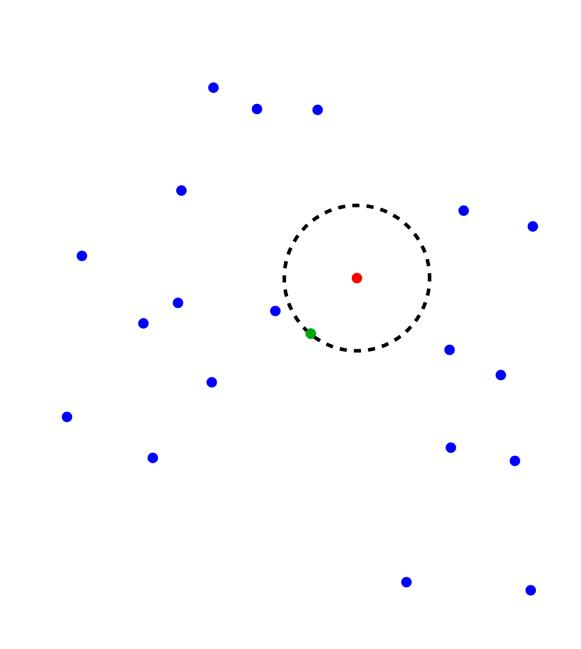
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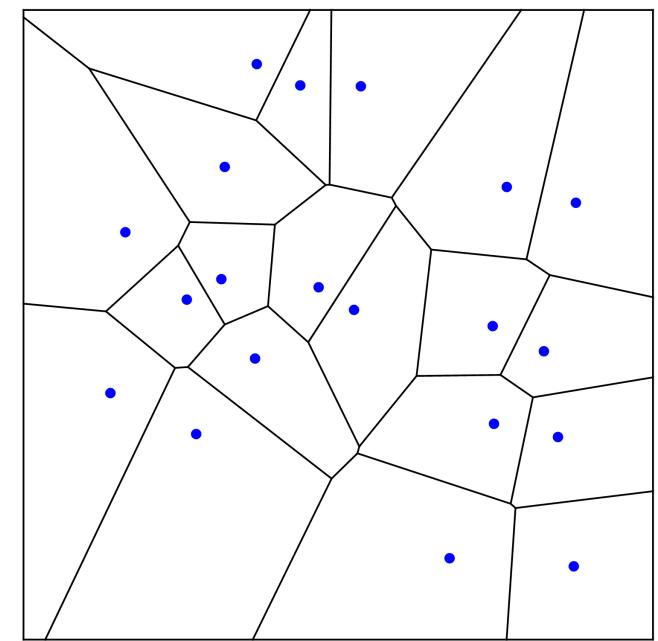
- Dataset: n points in R^d, r > 0
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- Space, query time



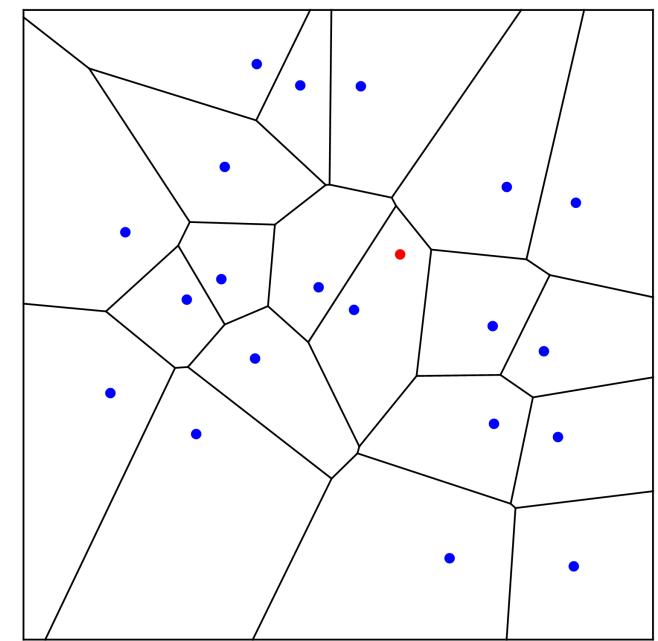
- Dataset: n points in R^d, r > 0
- **Goal:** a data point within **r** from a query
- Space, query time
- **d** = **2**, Euclidean distance
 - **O(n)** space
 - O(log n) time



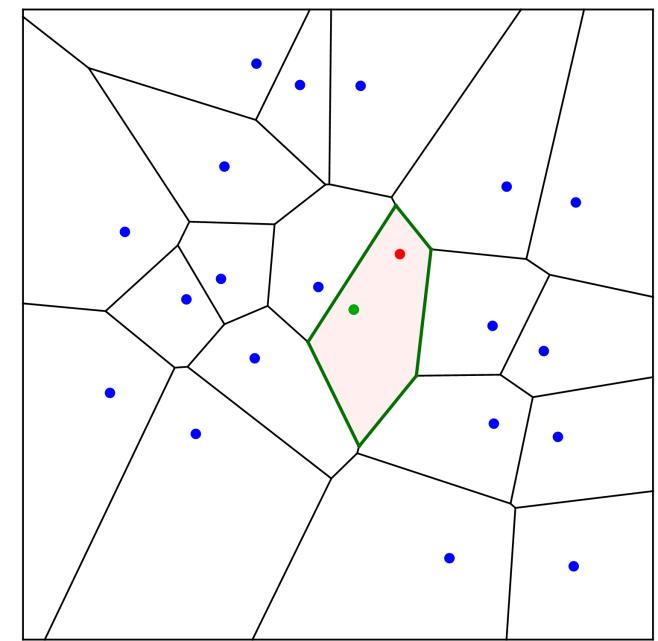
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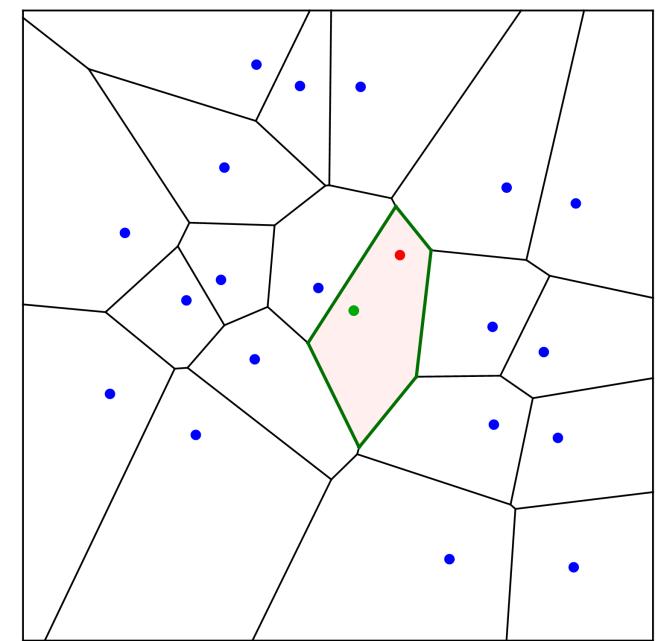
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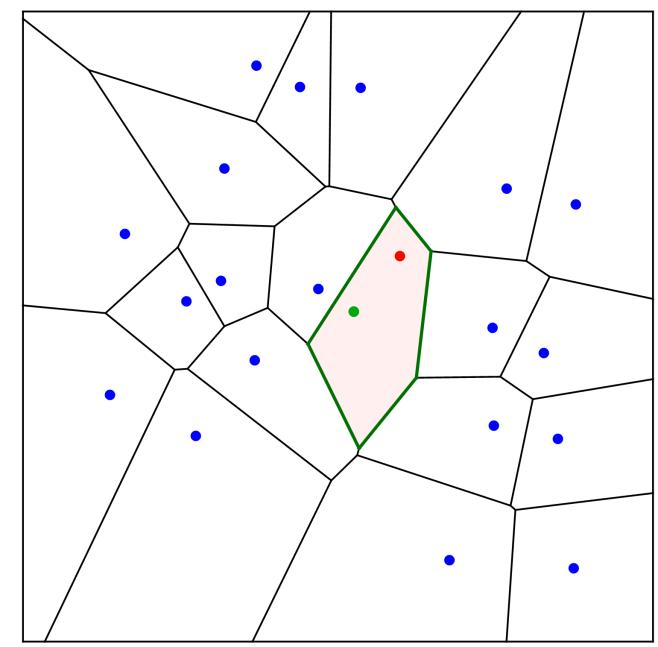
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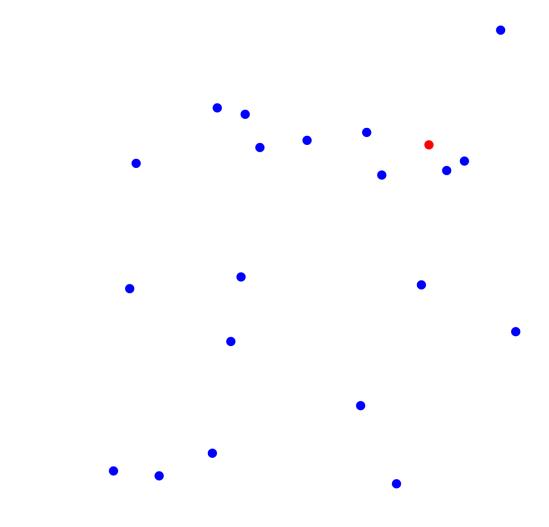
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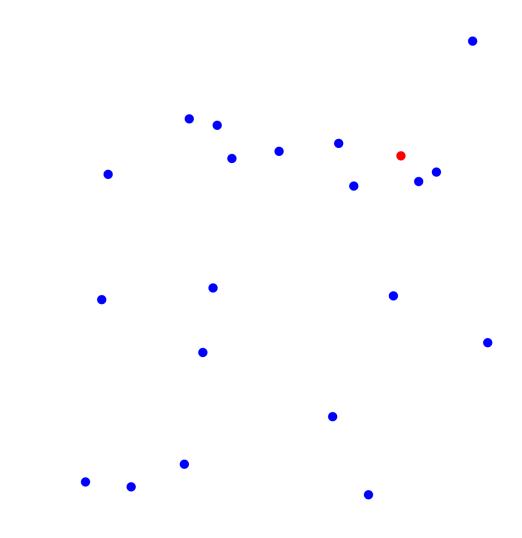
Detour: closest pair in *low* dimensions

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- distance threshold r > 0
- approximation c > 1

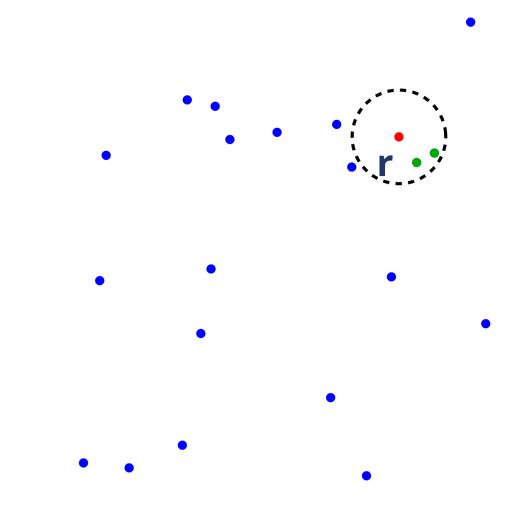
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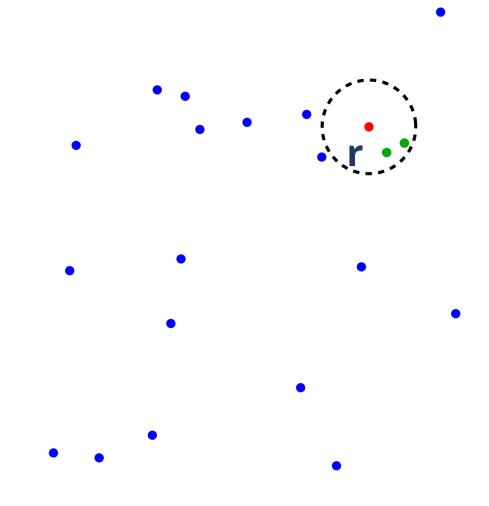
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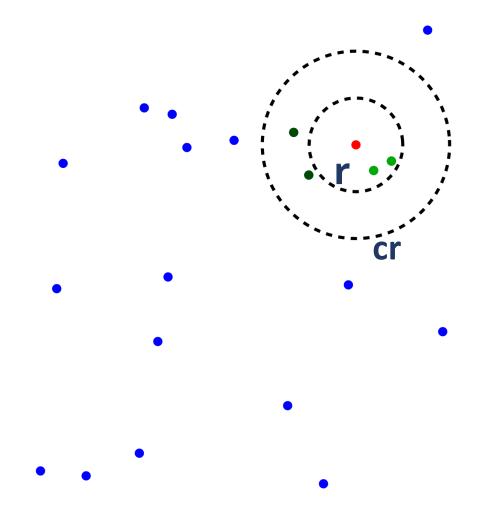
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- Optimization: Coordinate Descent [Dhillon, Ravikumar, Tewari 2011], Stochastic Gradient Descent [Hofmann, Lucchi, McWilliams 2015] etc

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all points and queries lie on a **unit sphere** in **R**^d

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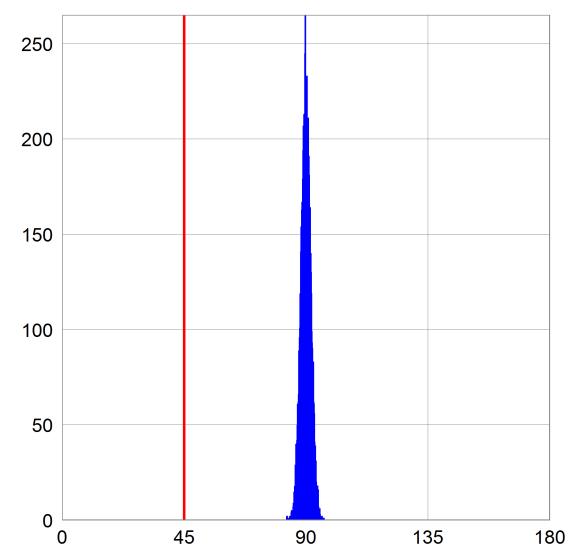
- Why interesting?
- In theory: can reduce general case to the spherical case [Andoni, R 2015]
- In practice:
 - Cosine similarity is widely used
 - Oftentimes, can *pretend* that the dataset lies on a sphere

• **Dataset: n** random points on a sphere

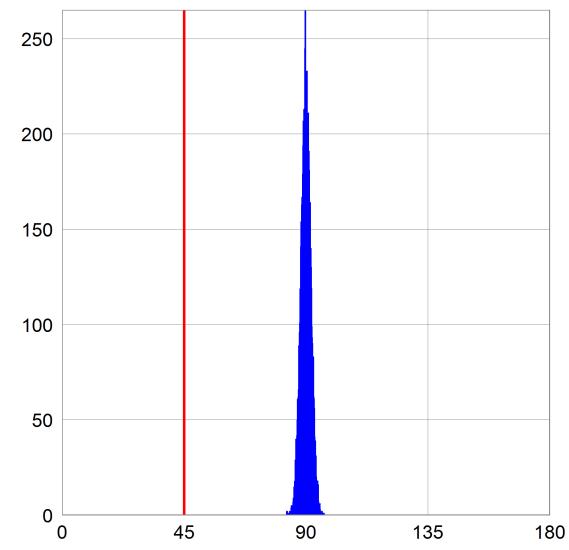
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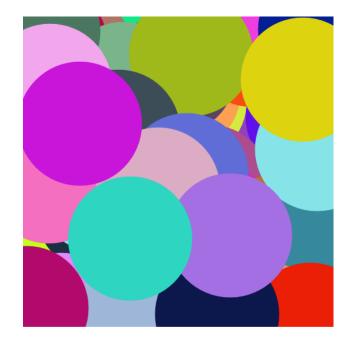
- **Dataset: n** random points on a sphere
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- Distribution of angles: near neighbor within 45 degrees, other data points at ~90 degrees!
- Instructive case to think about
 - [Andoni, R 2015]: a (delicate) reduction from general to random
 - Concentration of angles around **90** degrees happens in practice



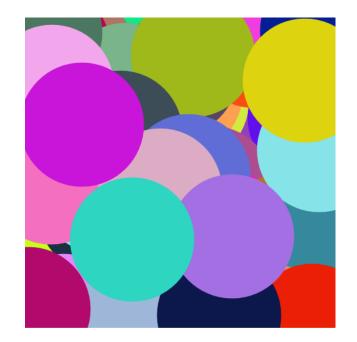
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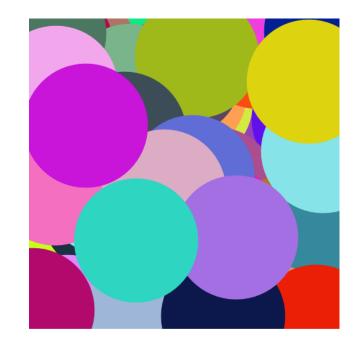
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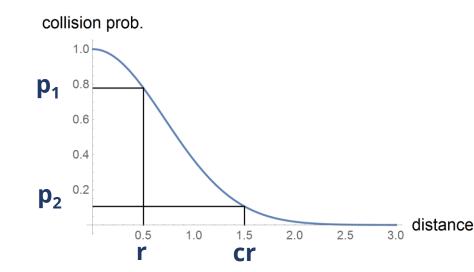


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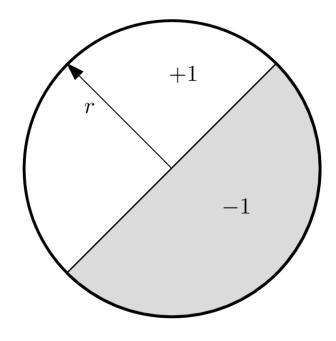




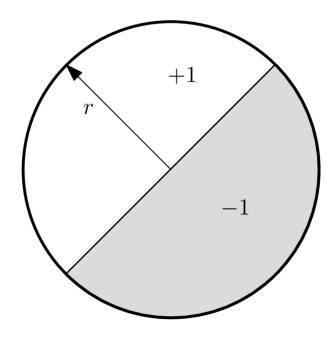
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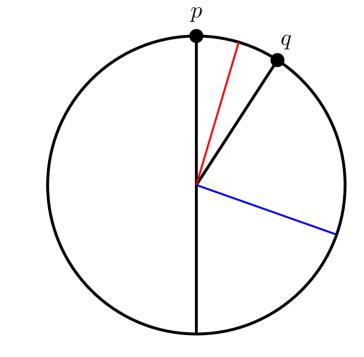
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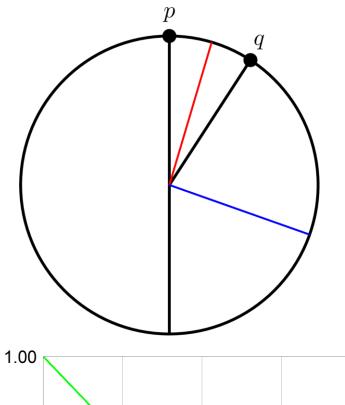
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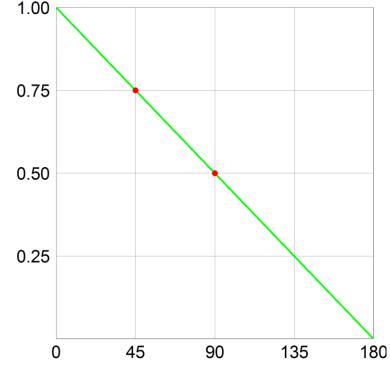


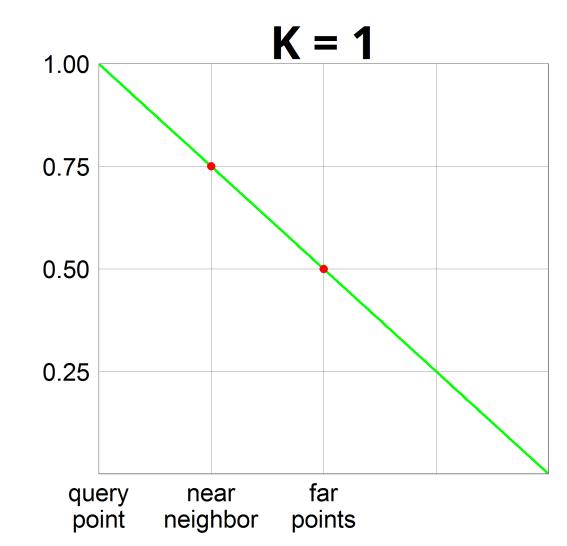
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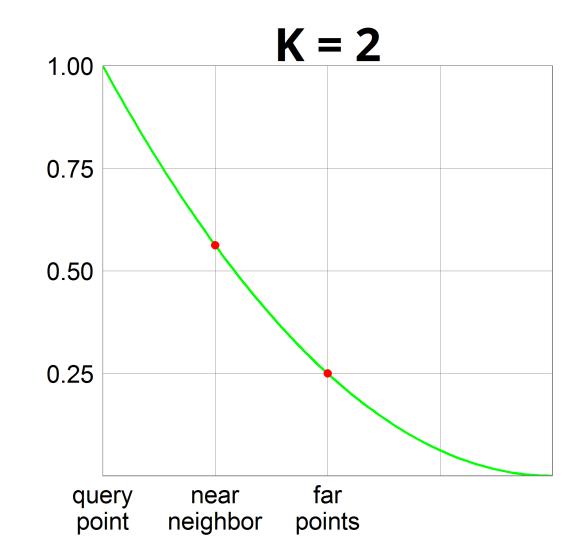


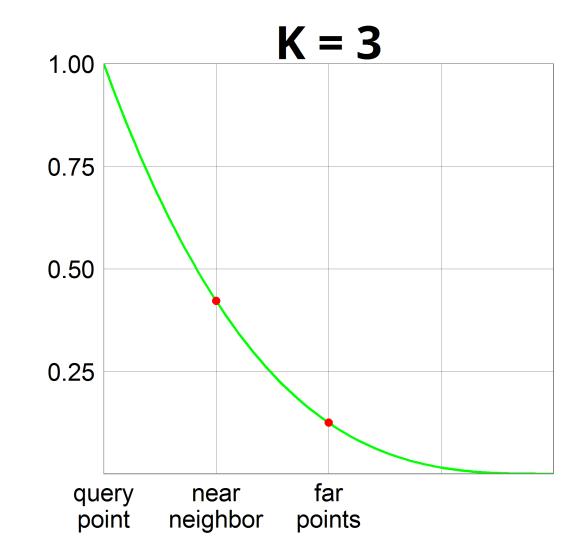
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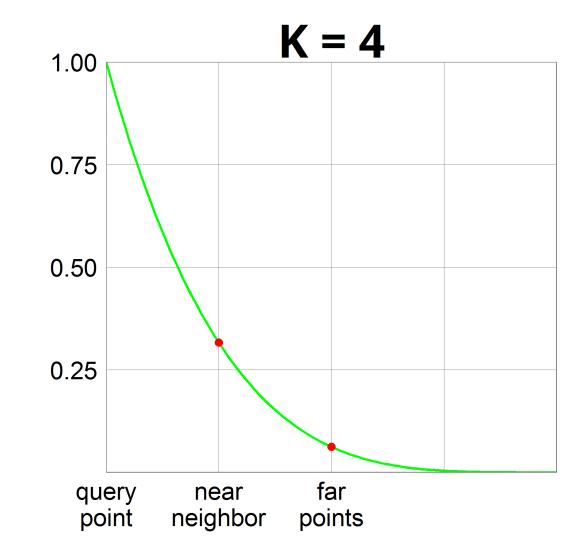


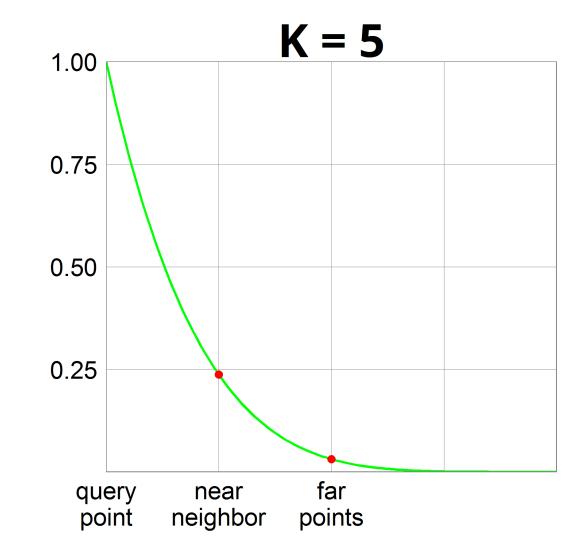


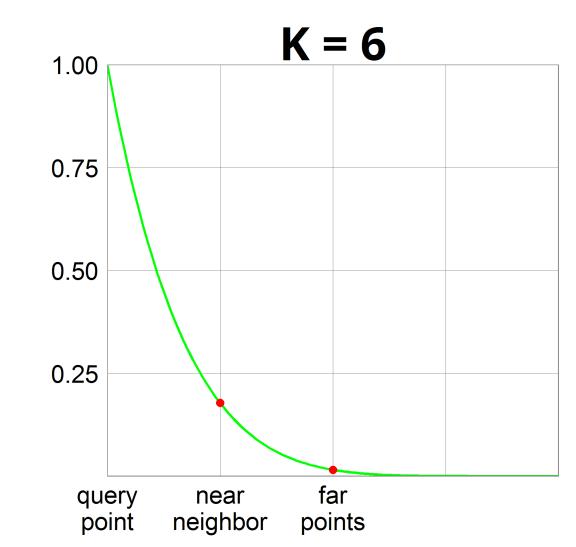




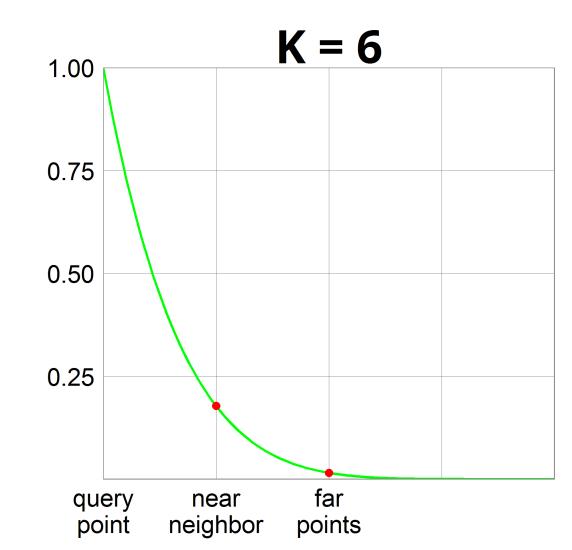




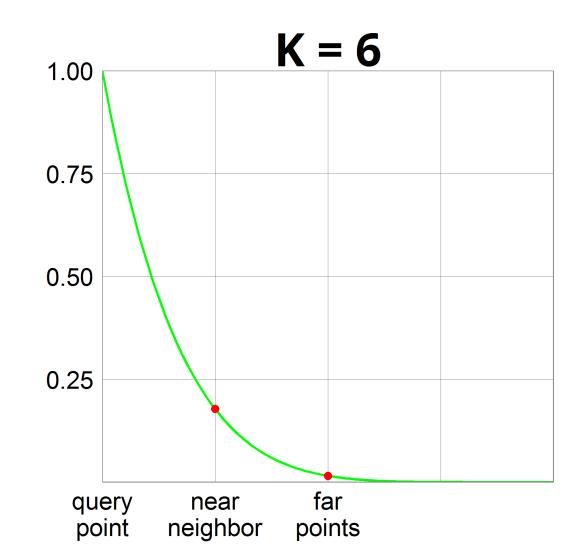




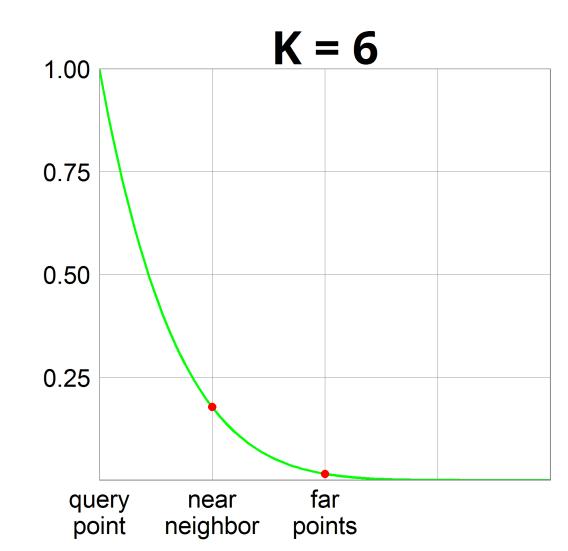
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- Overall: O(n^{1.42}) space, O(n^{0.42}) query time, K·L hyperplanes



In general **[Indyk, Motwani 1998]**: can always choose **K** (# of functions / table) and **L** (# of tables) to get space **O**(**n**¹⁺*P*) and query time **O**(**n**^{*P*}), where

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Recap:

- **p**₁ is collision probability for close pairs
- **p**₂ for far pairs

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Can we use this (significant) improvement in practice?

Optimal LSH family: Voronoi LSH

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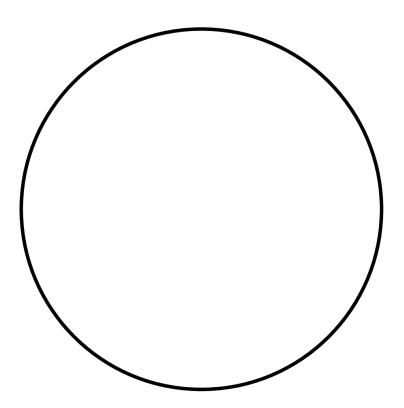
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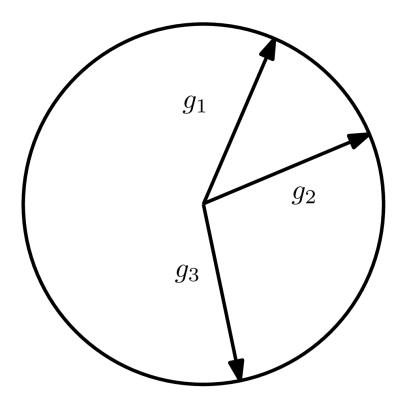
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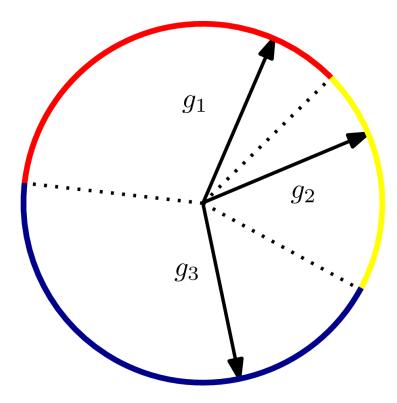
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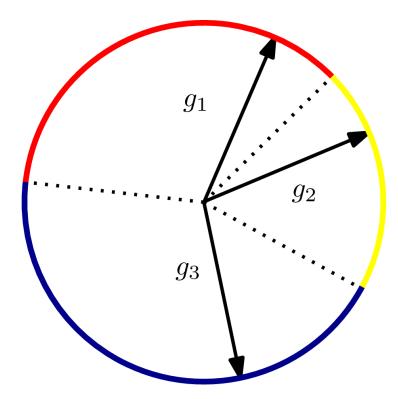
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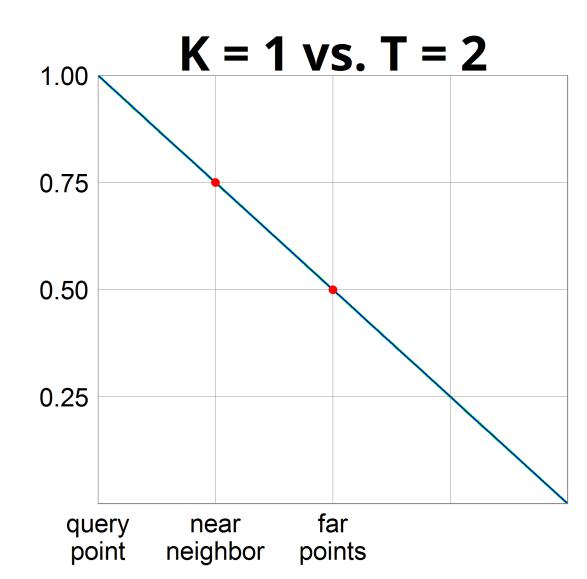


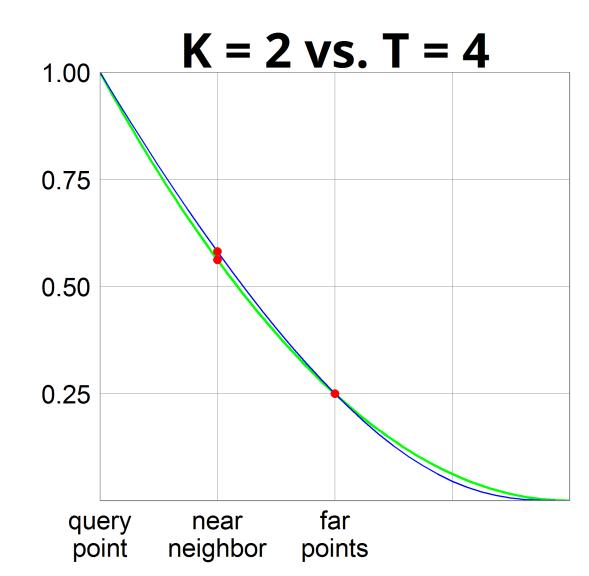
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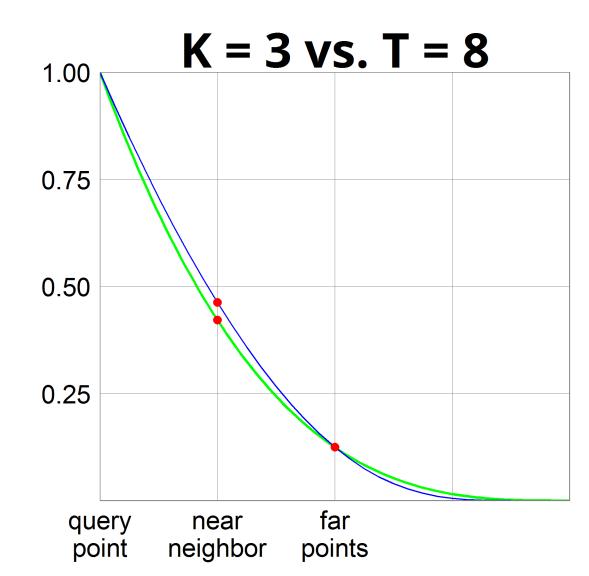
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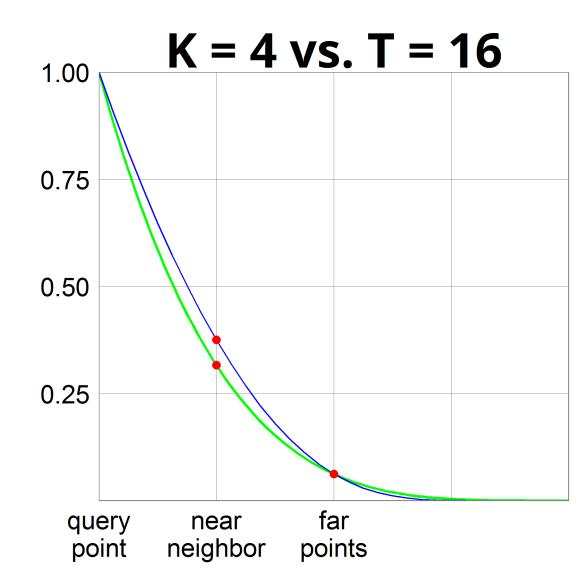
- Hash p into h(p) = argmax_{1≤i≤T} < p, g_i >
- **T** = **2** is simply Hyperplane LSH

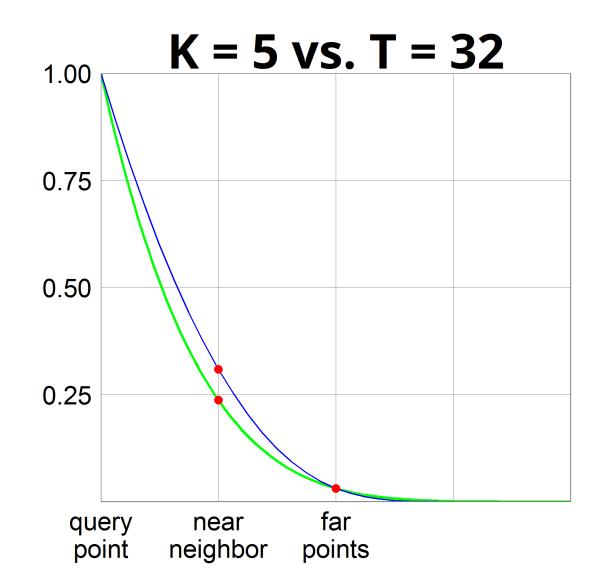


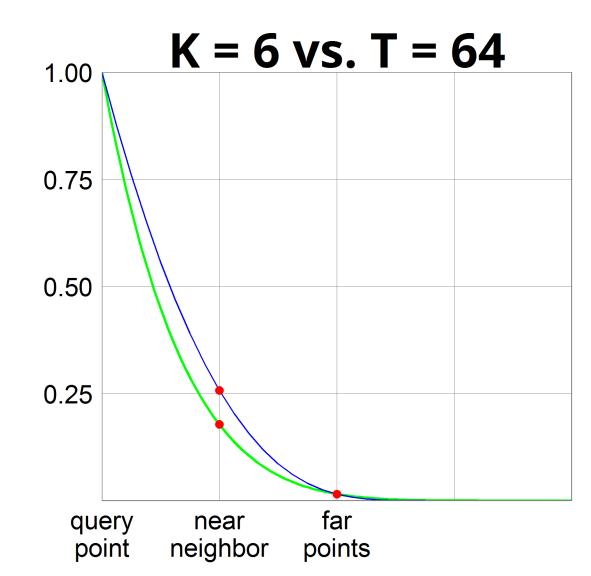






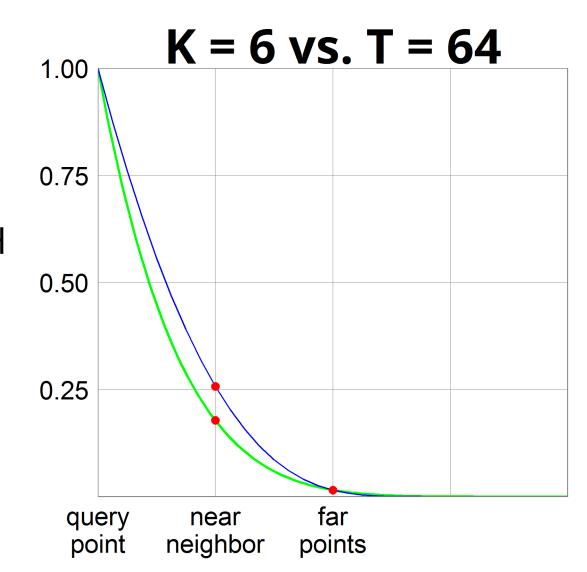






- Let us compare K hyperplanes vs. Voronoi LSH with T = 2^K (in both cases K-bit hashes)
- As T grows, the gap between Hyperplane LSH and Voronoi LSH increases and

ρ = ln(1/p₁) / ln(1/p₂) approaches **0.18**



Practicality







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- Can practice benefit from theory?

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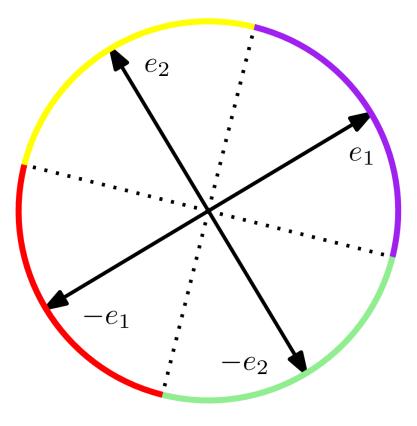
No!

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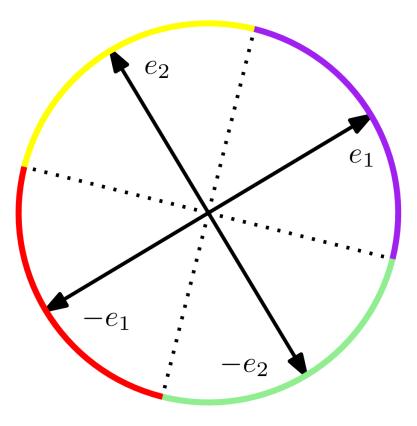
This work: yes!

- Cross-polytope LSH introduced by [Terasawa, Tanaka 2007]:
 - To hash **p**, apply a *random rotation* **S** to **p**
 - Set hash value to a vertex of a cross-polytope {±e_i} closest to Sp

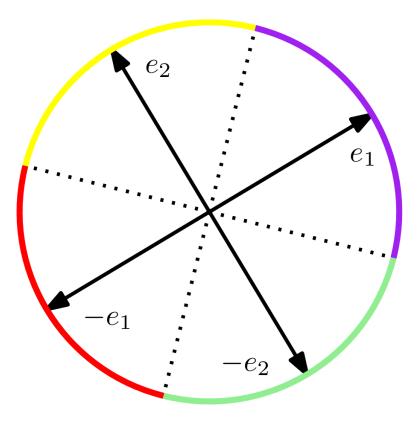
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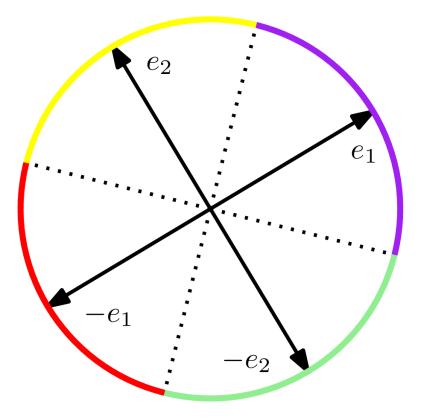
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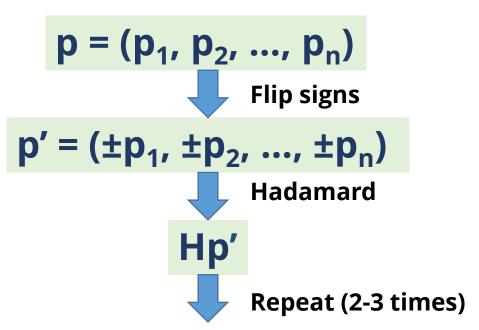
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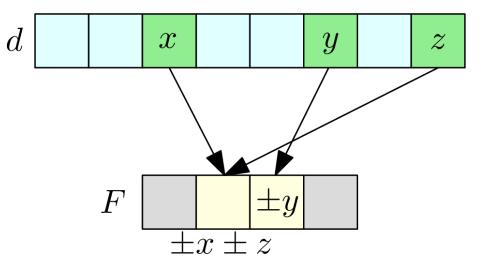
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- A similar procedure for Cross-polytope LSH (more complicated, since the range is non-binary)

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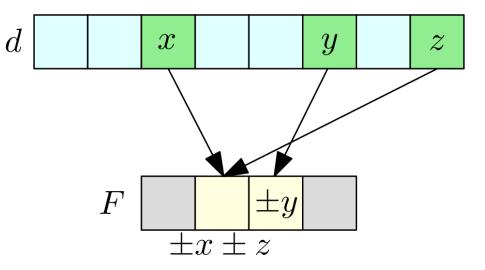
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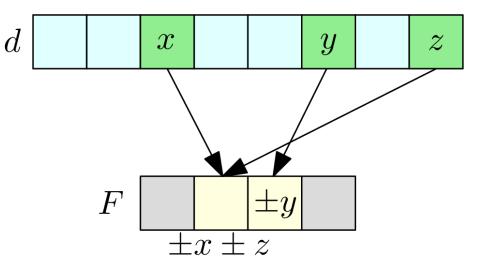
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- Available at http://falconn-lib.org together with Python bindings
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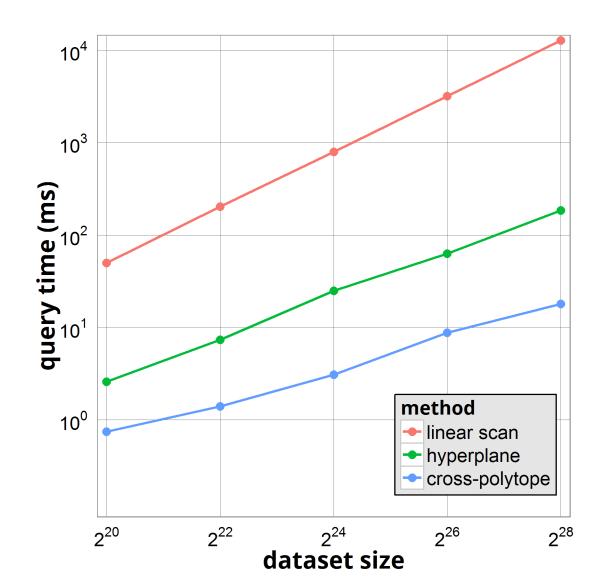
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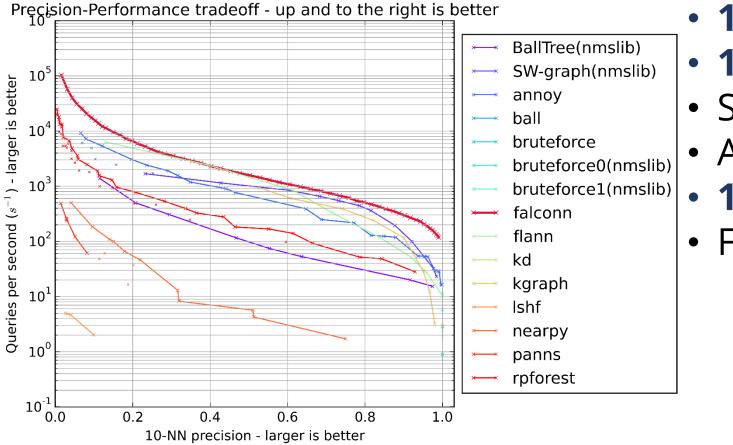
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Precision-Performance tradeoff - up and to the right is better BallTree(nmslib) SW-graph(nmslib) 10^{5} Queries per second (s^{-1}) - larger is better annoy ball 10^{4} bruteforce bruteforce0(nmslib) 10^{3} bruteforce1(nmslib) falconn flann 10^{2} kd kgraph 10^{1} lshf nearpy 10^{0} panns rpforest $10^{-1} \\ 0.0$ 0.2 0.4 0.6 0.8 1.0

10-NN precision - larger is better

[Pennington, Socher, Manning 2014] n = 1.2M, d = 100, aim at 10 nearest neighbors



- 16-bit hashes
- 1...1400 tables
- Single probe
- Accuracy 0.016...0.99
- 10µs to 8.5ms query
- From **5 Mb** to **7 Gb**

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- For the further progress, need evaluation time sublinear in the range size!
 - Complexity of "decoding" for almost-orthogonal vectors

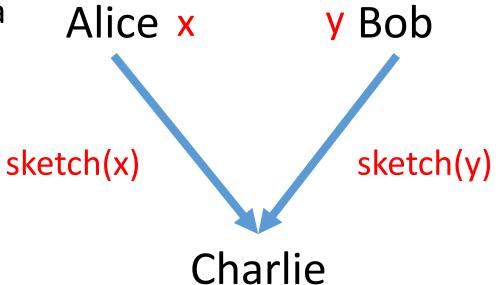
ANN with fast query time via sketches

Sketching metrics

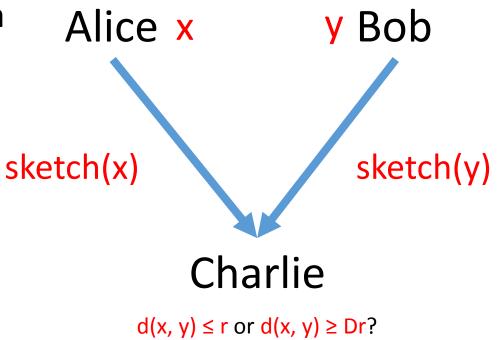
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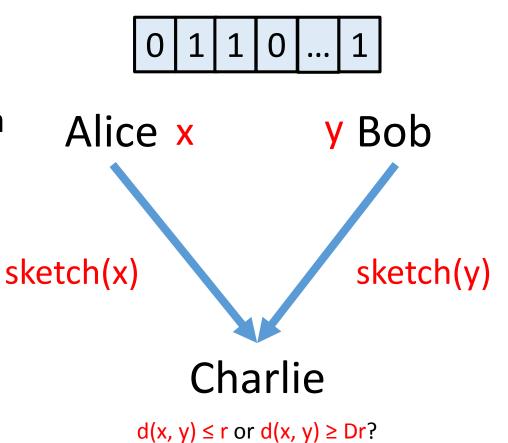
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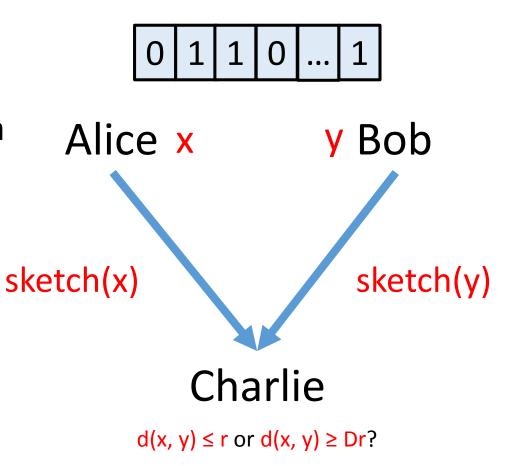
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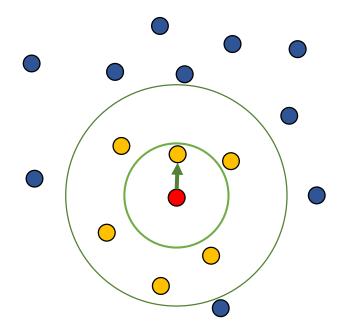
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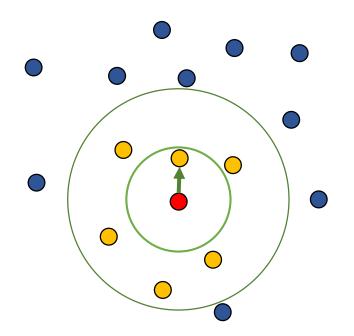
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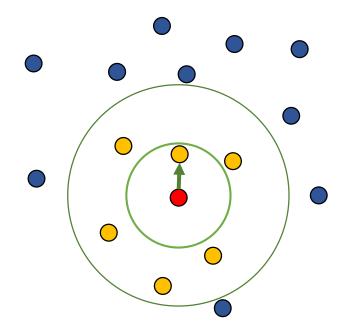
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 - Given n-point dataset P
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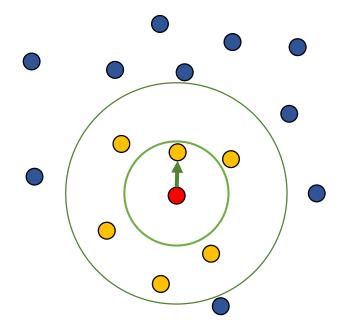
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- For many metrics: the only approach



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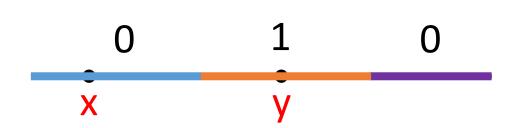
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- For p > 2 sketching l_p is somewhat hard (Bar-Yossef, Jayram, Kumar, Sivakumar 2002), (Indyk, Woodruff 2005)
 - To achieve D = O(1) one needs sketch size to be $s = \Theta^{(d^{1-2/p})}$

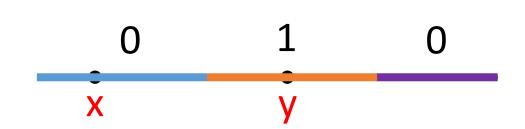
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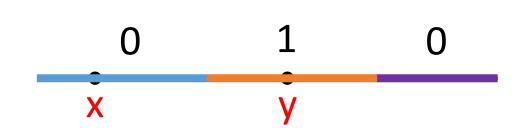
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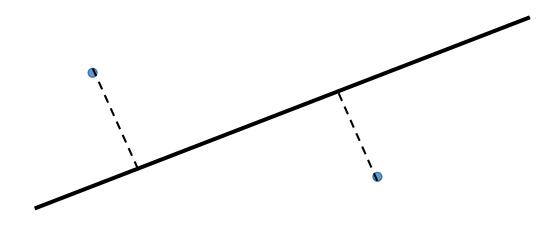


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Summary

- Space: **n**^{O(1/ε^2)}
- Query time: poly(log n / ε)